

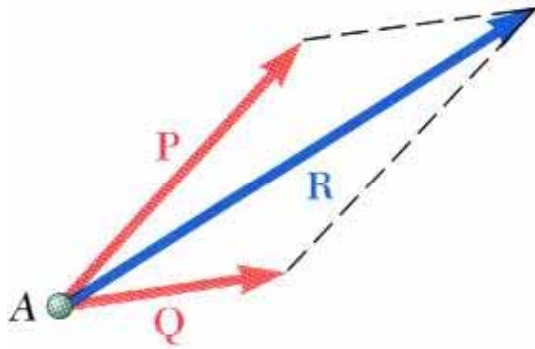
Section 8: Statics - Basics

Fundamental Concepts

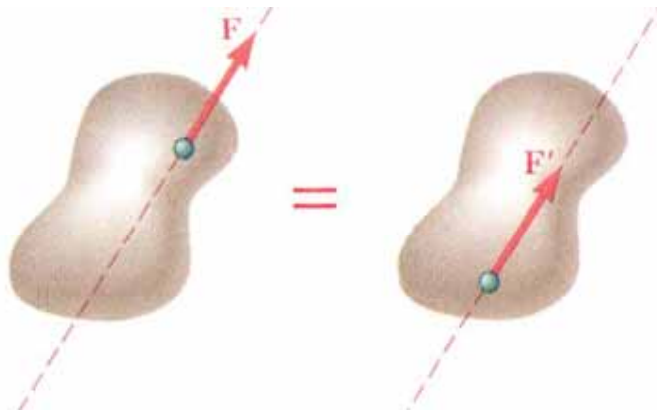
- *Time* - definition of an event requires specification of the time and position at which it occurred.
- *Mass* - used to characterize and compare bodies, e.g., response to earth's gravitational attraction and resistance to changes in translational motion.
- *Force* - represents the action of one body on another. A force is characterized by its point of application, magnitude, and direction, i.e., a force is a vector quantity.

In Newtonian Mechanics, space, time, and mass are absolute concepts, independent of each other. Force, however, is not independent of the other three. The force acting on a body is related to the mass of the body and the variation of its velocity with time.

Fundamental Principles



- *Parallelogram Law*



- *Principle of Transmissibility*

- *Newton's First Law:* If the resultant force on a particle is zero, the particle will remain at rest or continue to move in a straight line.
- *Newton's Second Law:* A particle will have an acceleration proportional to a nonzero resultant applied force.

$$\vec{F} = m\vec{a}$$

- *Newton's Third Law:* The forces of action and reaction between two particles have the same magnitude and line of action with opposite sense.

- *Newton's Law of Gravitation:* Two particles are attracted with equal and opposite forces,

$$F = G \frac{Mm}{r^2} \quad W = mg, \quad g = \frac{GM}{R^2}$$

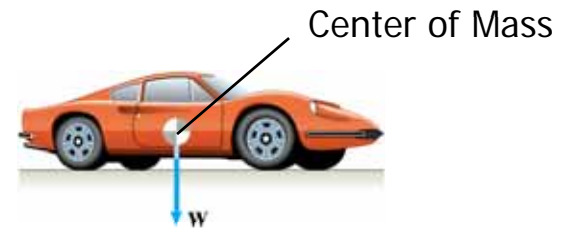
Fundamental Equations

- Statics implies equilibrium
- No Acceleration $\rightarrow \Sigma F = ma = 0$
 - Sum of Forces in all directions is ZERO!
 - $\Sigma F_x = 0$
 - $\Sigma F_y = 0$
 - $\Sigma F_z = 0$
- No Rotation $\rightarrow \Sigma M = 0$
 - Sum of Moments in all directions is ZERO!

More Force Terminology

– Gravity

- $W = m \cdot g$
- $G = 9.81 \text{ m/s}^2 = 32.2 \text{ ft/s}^2$

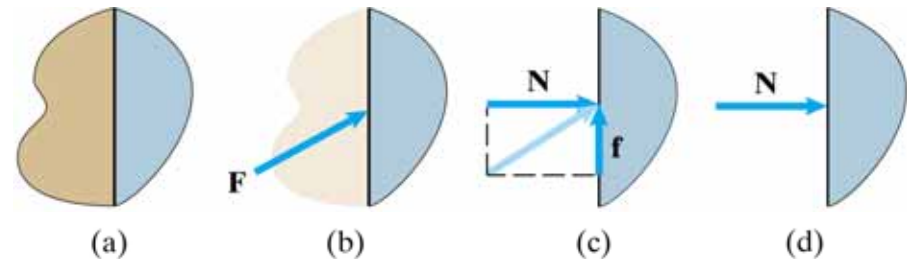
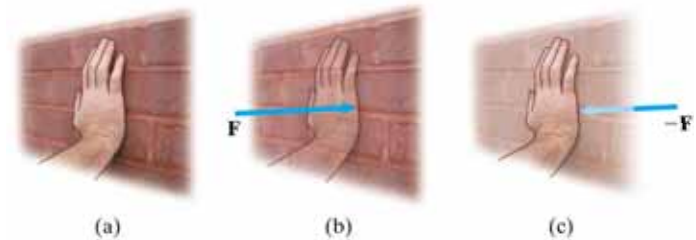


– Body Force

- Ex: Gravity

– Surface Force

- Normal Force (N)
- Frictional Force (f)



2.1 Scalars & Vectors

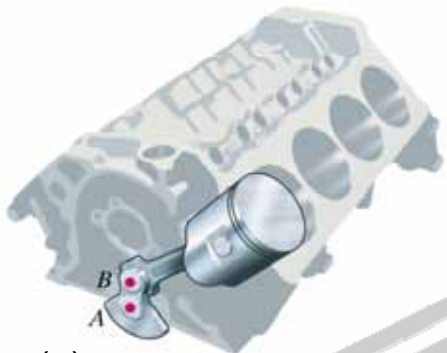
- **Scalar** – a physical quantity that is completely described by a real number
 - E.g. Time, mass
- **Vector** – both **magnitude** (nonnegative real number) & **direction**
 - E.g. Position of a point in space relative to another point, forces
 - Represented by boldfaced letters: **U**, **V**, **W**, ...
 - Magnitude of vector $\mathbf{U} = |\mathbf{U}|$

2.1 Scalars & Vectors

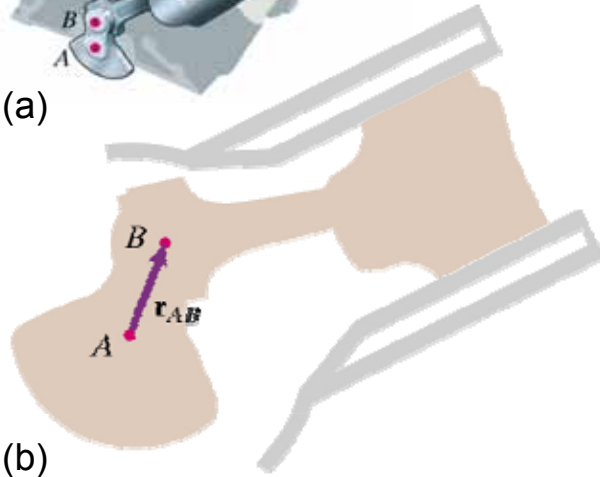
– Graphical representation of vectors: **arrows**

- Direction of arrow = direction of vector
- Length of arrow

\propto magnitude of vector



(a)



(b)

8-7

- **Example:**

– \mathbf{r}_{AB} = position of point B relative to point A

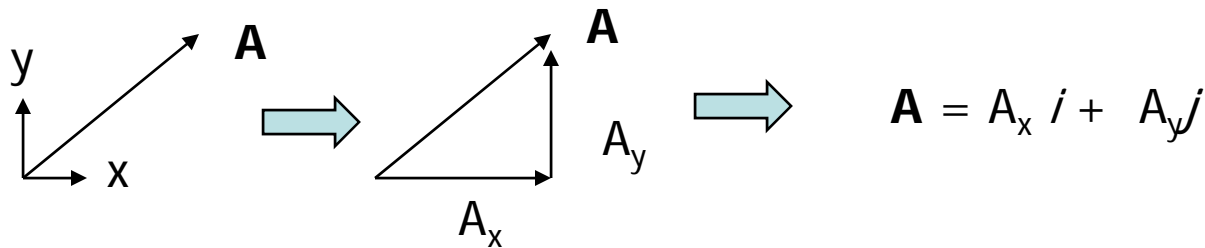
– Direction of \mathbf{r}_{AB} = direction from point A to point B

– $|\mathbf{r}_{AB}|$ = distance between 2 points

From: Katafygiotis

Vector Manipulation

- Components

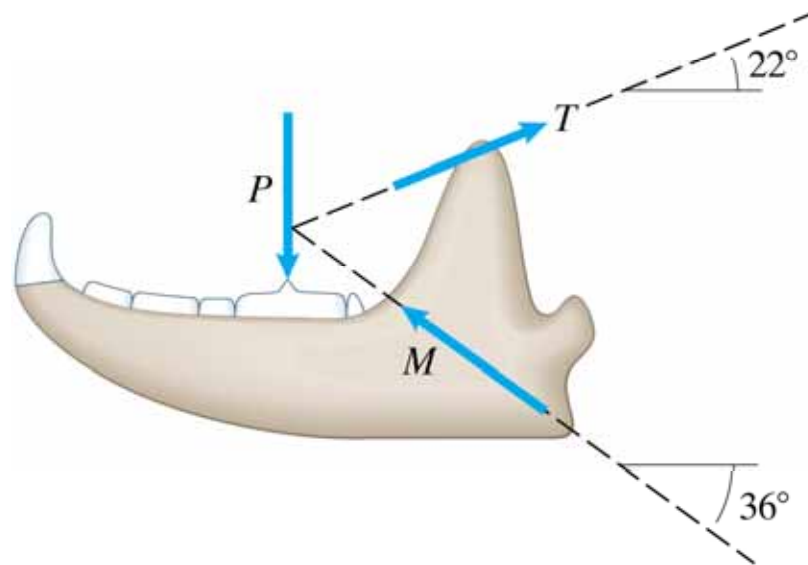


- Addition $\Rightarrow \mathbf{A} + \mathbf{B} = (A_x + B_x) \mathbf{i} + (A_y + B_y) \mathbf{j}$

- Scalar Multiplication $\Rightarrow c\mathbf{A} = cA_x \mathbf{i} + cA_y \mathbf{j}$

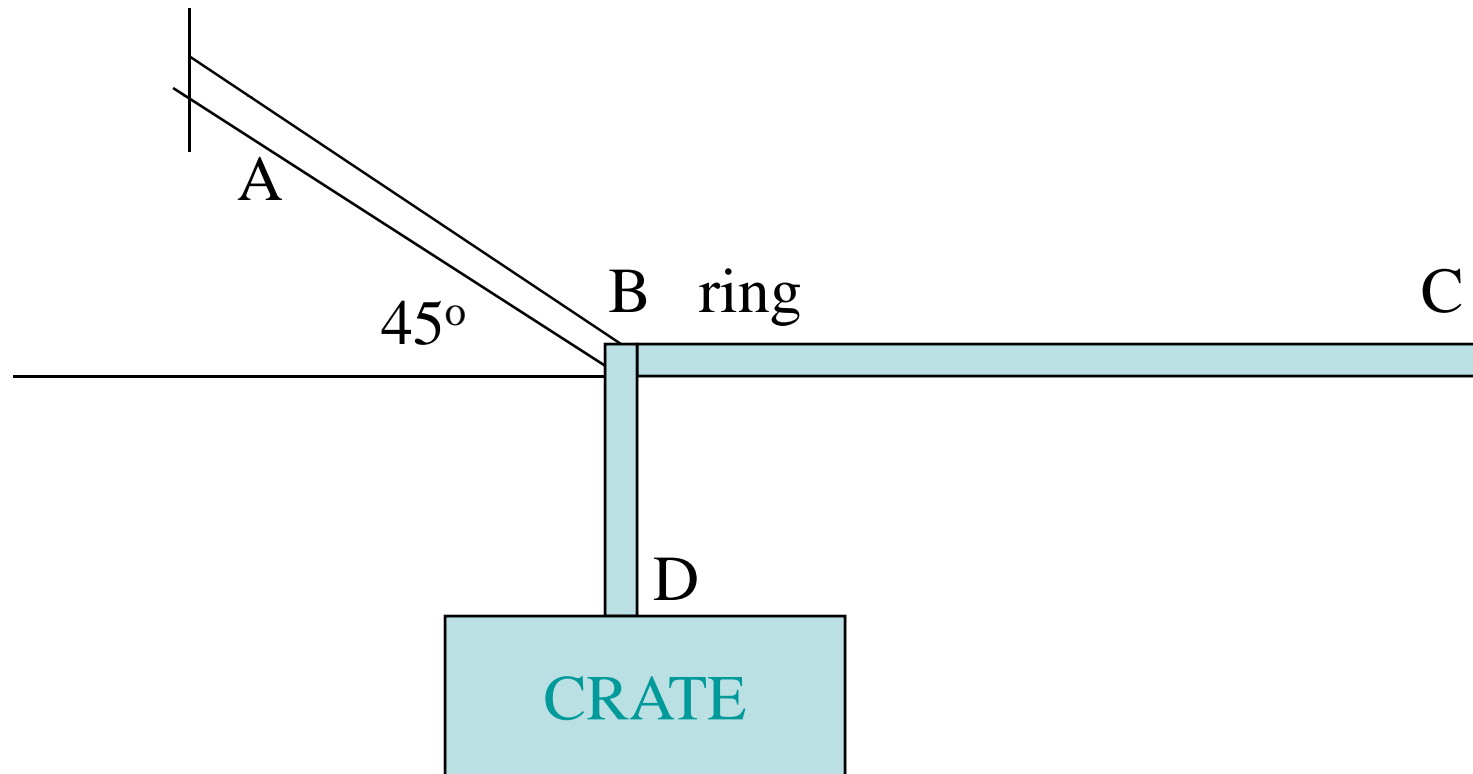
Example Problem

- 2. A zoologist estimates that the jaw of a predator is subjected to a force P as large as 800 N. What forces T and M must be exerted by the temporalis and masseter muscles to support this value of P ?

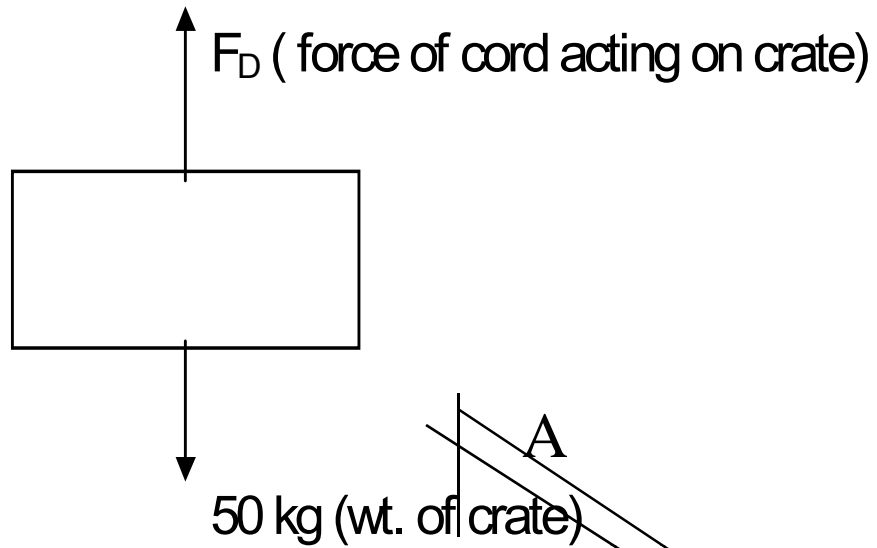


Example

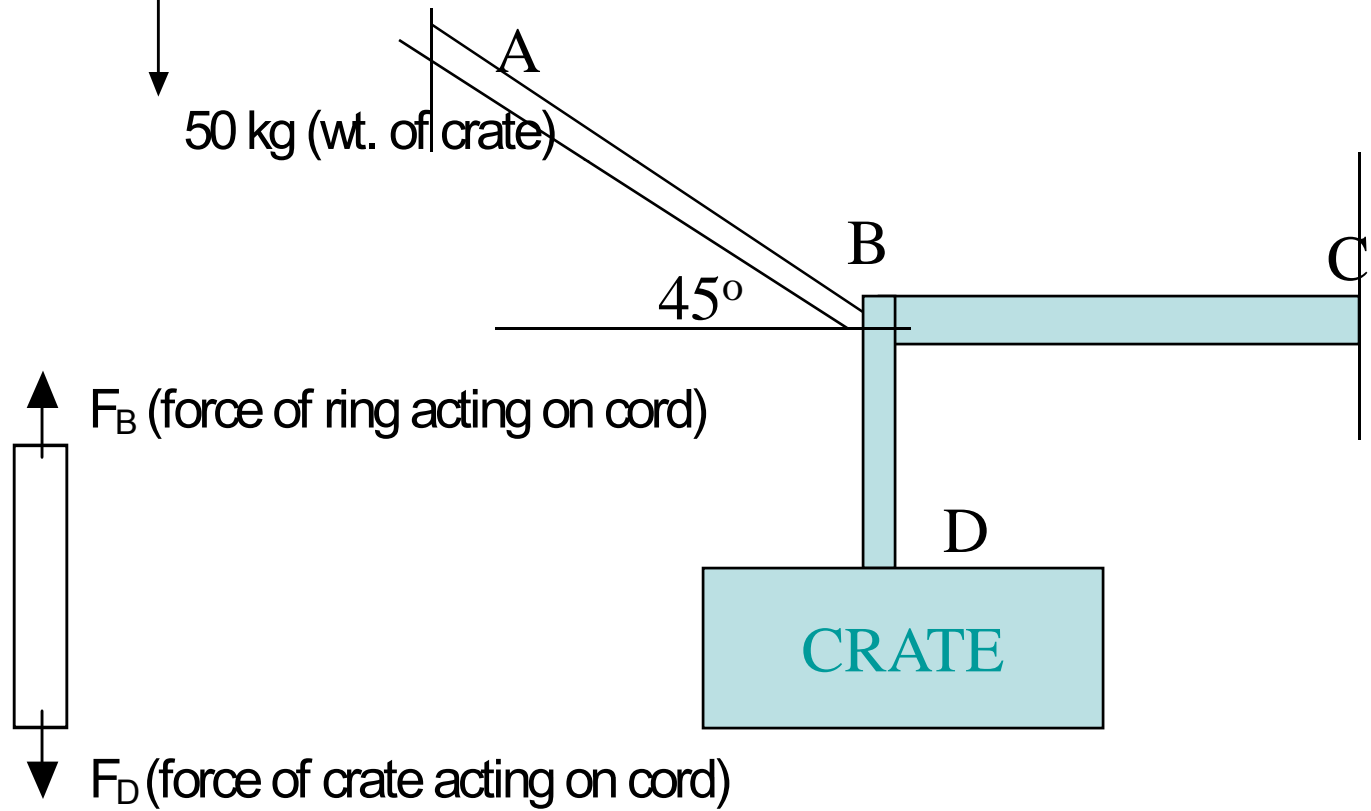
- The crate below has a weight of 50 kg. Draw a free body diagram of the crate, the cord BD and the ring at B.



(a) Crate

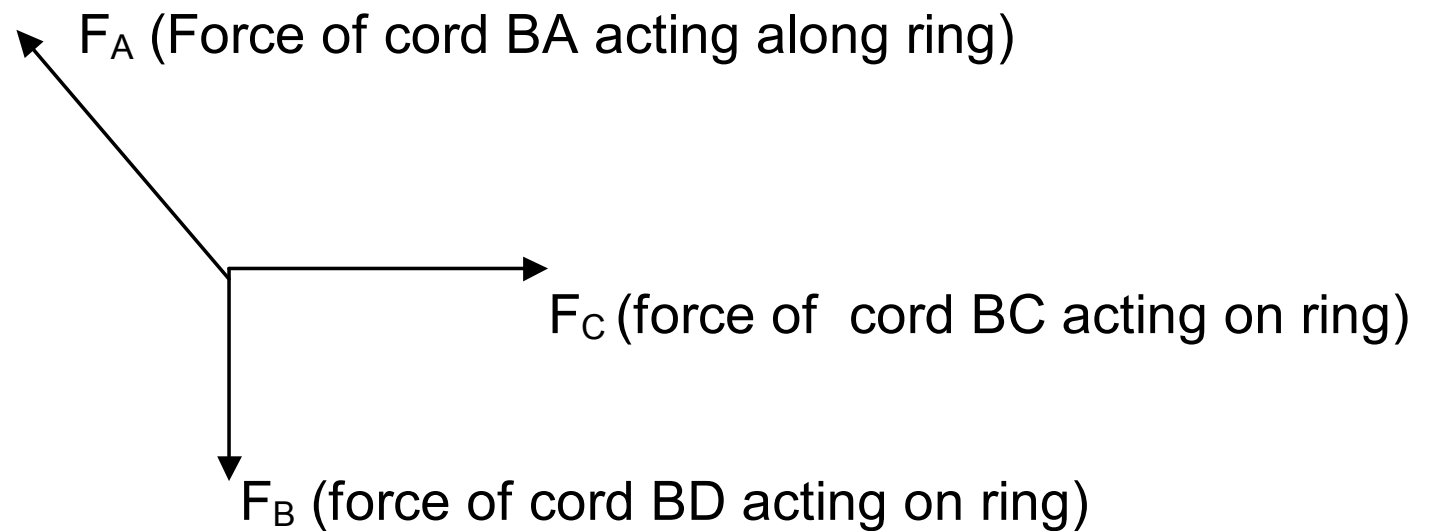


(b) Cord BD



Solution Contd.


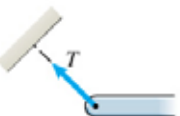



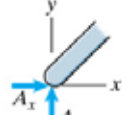

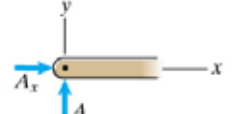





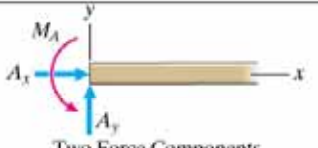
(c) Ring



Supports

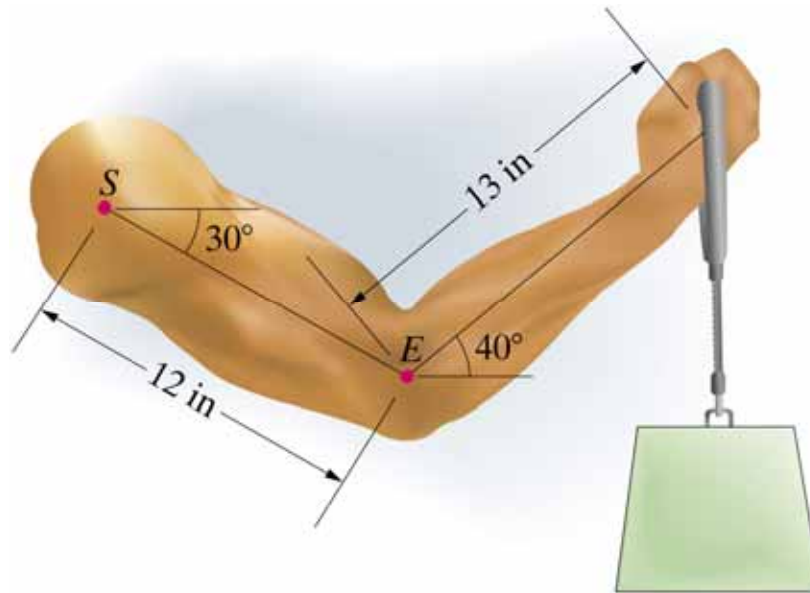
- When drawing free body diagram...
 - If you remove a support, you must replace it with appropriate reaction forces
 - Think: What movements does the support restrict?

Table 5.1

Supports	Reactions
 <p>Rope or Cable Spring</p>	 <p>A Collinear Force</p>
 <p>Contact with a Smooth Surface</p>	 <p>A Force Normal to the Supporting Surface</p>
 <p>Contact with a Rough Surface</p>	 <p>Two Force Components</p>
 <p>Pin Support</p>	 <p>Two Force Components</p>
 <p>Roller Support Equivalents</p>	 <p>A Force Normal to the Supporting Surface</p>
 <p>Constrained Pin or Slider</p>	 <p>A Normal Force</p>
 <p>Fixed (Built-in) Support</p>	 <p>Two Force Components and a Couple</p>

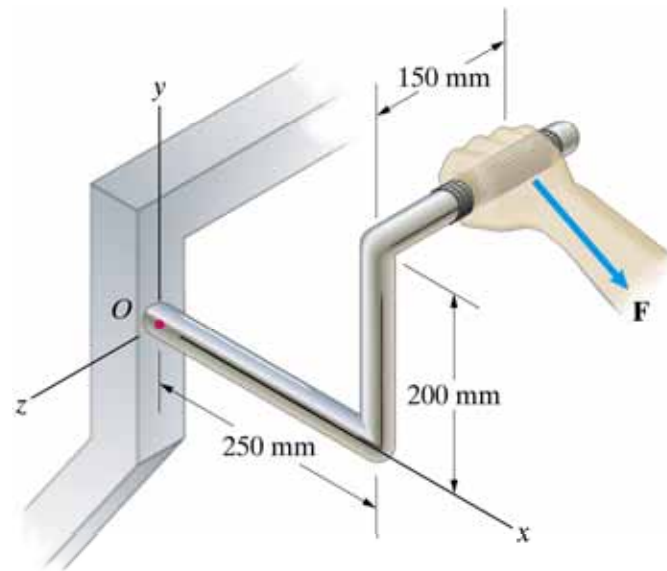
Homework Problem 8.1

- 6. The moment exerted about point E by the weight is 299 lb-in. What moment does the weight exert about point S?



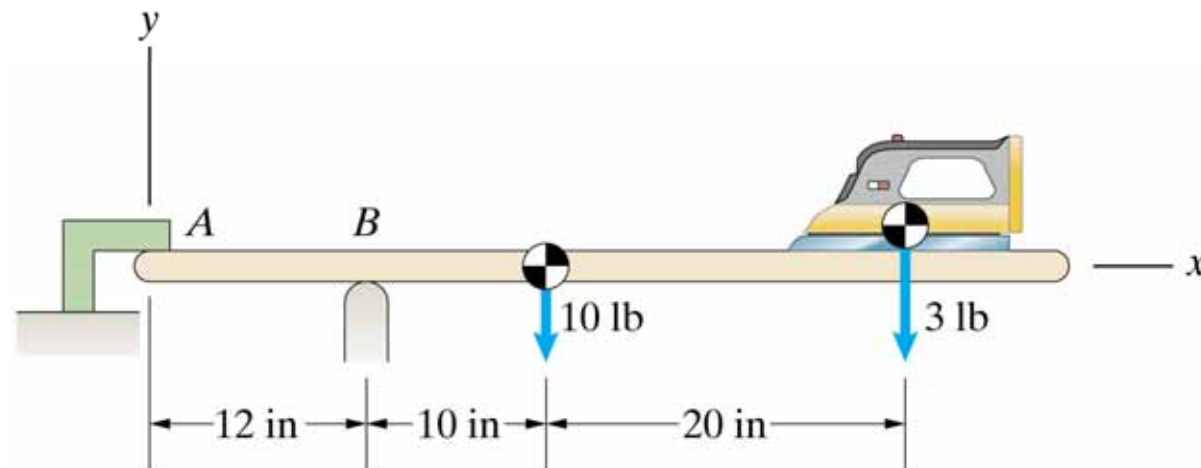
Homework Problem 8.2

- 7. The force F points in the direction of the unit vector $e = \frac{2}{3}i - \frac{2}{3}j + \frac{1}{3}k$. The support at O will safely support a moment of 560 N-m magnitude. Based on this criterion, what is the largest safe magnitude of F ?



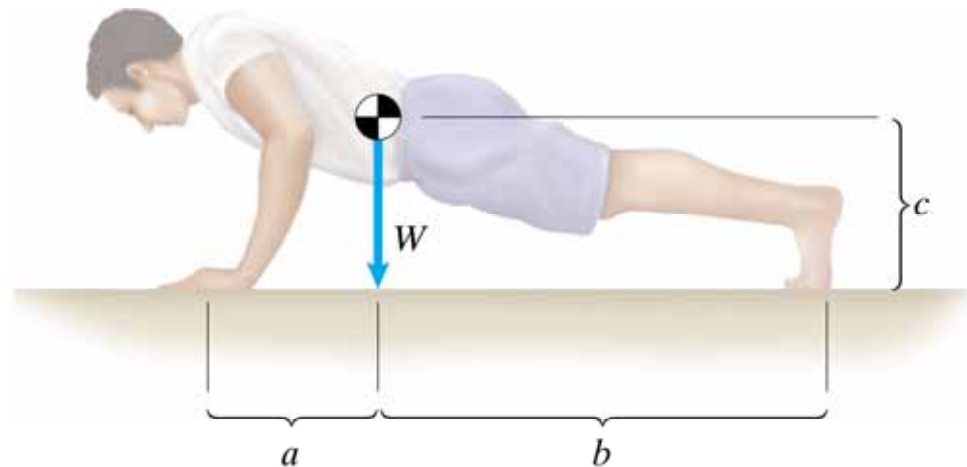
Homework Problem 8.3

- 8. The ironing board has supports at A and B that can be modeled as roller supports. Draw a free body diagram of the ironing board and determine the reactions at A and B.



Homework Problem 8.4

- 9. The person doing push-ups pauses in the position shown. His mass is 80 kg. Assume that his weight, W , acts at the point shown. The dimensions shown are $a = 250$ mm, $b = 740$ mm, and $c = 300$ mm. Find the normal force exerted by the floor on each hand and each foot.



Homework Problem 8.5

- A person exerts a 60-lb force F to push a crate onto a truck. Express F in terms of components.

